Contents

1 Introduction **1**
- 1.1 Aim and Scope 4
- 1.2 Organisation of this Work 6

2 State-of-the-Art Real-Time Simulation Methodologies **7**
- 2.1 Introduction 7
- 2.2 Development of Digital Real-Time Simulators 8
- 2.3 Controller Hardware-in-the-Loop (CHIL) Systems 12
- 2.4 Power Hardware-in-the-Loop (PHIL) Systems 14
  - 2.4.1 Principles for PHIL Simulation Systems 14
  - 2.4.2 Flexibility and Challenges 16
- 2.5 Summary 17

3 Interfacing Methods for PHIL Simulation Systems **18**
- 3.1 Introduction 18
- 3.2 Principles and Criteria for Modelling of PHIL Simulation Systems 19
  - 3.2.1 Fundamental Principles 19
  - 3.2.2 Theoretic Evaluations and System Properties 23
  - 3.2.3 Single-Input Single-Output (SISO) PHIL Systems 31
  - 3.2.4 Multiple-Input Multiple-Output (MIMO) PHIL Systems . 32
- 3.3 Methods to Stabilise PHIL Simulation Systems 34
  - 3.3.1 Hardware Inductance Addition (HIA) Method 34
  - 3.3.2 Feedback Current Filtering (FCF) Method 36
  - 3.3.3 Partial Shifting Impedance (PSI) Method 39
- 3.4 Conclusions 41

4 Interfacing Topologies for PHIL Simulation Systems **42**
- 4.1 Introduction 42
- 4.2 Interfacing Topologies for Single-Rate (SR) PHIL Simulation . . . 43
  - 4.2.1 Ideal Transformer Method (ITM) Interfacing Topology . . 44
  - 4.2.2 Partial Circuit Duplication (PCD) Interfacing Topology . . 47

4.2.3 Damping Impedance Method (DIM) Interfacing Topology 49
4.3 The Multi-Rate Partitioning (MRP) Interfacing Topology 52
4.3.1 Idea and Architecture 53
4.3.2 Interface Characteristics for PHIL Systems 55
4.3.3 Analytical Comparison of SR and MRP Interfaces for PHIL Simulation 62
4.3.4 Summary 72
4.4 Conclusions 73

5 Validation Platform for Interfacing Methods of PHIL Systems 75
5.1 Introduction 75
5.2 Verification, Validation, and Testing Procedures for PHIL Simulation Systems 76
5.2.1 The Verification and Validation Process 76
5.2.2 Proposed Testing Procedures 81
5.3 Case Studies for PHIL Simulation with SR and MRP Interface . . 89
5.3.1 Theoretical Analysis of a Basic Electric Circuit 89
5.3.2 Investigations of Active Controls in Distributed Networks 100
5.3.3 Transient Behaviour and Stability for Nonlinear Systems . 114
5.4 Conclusions 124

6 Conclusions and Outlook 126
6.1 Conclusions 126
6.2 Outlook 129

A Real-Time Simulators and Laboratory Setup 130
A.1 Digital Real-Time Simulators 130
A.2 Laboratory Setup 136
A.3 Dynamics and Modelling of Key Components 142
A.3.1 Power Amplification Topologies 142
A.3.2 Measurement Apparatus 144
A.3.3 Safety Measures for PHIL Simulation 146

B Selected Real-Time Simulation Results 148
B.1 Voltage-Type SISO Interface Topologies 148
B.2 Current-Type SISO Interface Topologies 149
B.3 Voltage-Type MIMO Interface Topologies 149
B.4 Dual Feedback and Feedforward Filtering Methods 152
B.5 Delay Analysis of SR and MRP Interface for PHIL Simulation . . 154
B.6 Extended Evaluations for Case Studies 157
B.6.1 Ad Case Study I: Additional Setups 157

B.6.2 Ad Case Study II: Additional Active Control Scenarios . . 164

C Nomenclature and Terminology **180**

Bibliography **187**